

PC6DIO

CANopen
IO Module



User Manual



05/08/2014 V1.0

P.O.Box 164
Seven Hills 1730
NSW
AUSTRALIA

Tel: +61 2 96248376
Fax: +61 2 9620 8709
Email: proconel@proconel.com
Web: www.proconel.com

Disclaimer

Procon Electronics makes no representations or warranties with respect to the contents hereof. In addition, information contained herein are subject to change without notice. Every precaution has been taken in the preparation of this manual. Nevertheless, Procon Electronics assumes no responsibility, express or implied, for errors or omissions or any damages resulting from the use of the information contained in this publication.

All trademarks belong to their respective owners.

TABLE OF CONTENTS

1.	INTRODUCTION	5
2.	TECHNICAL SPECIFICATION	6
3.	PHYSICAL INFORMATION	7
3.1	PHYSICAL DIMENSIONS	7
3.2	DIN RAIL BUS ADAPTOR.....	8
3.3	INSTALLING THE MODULE ONTO THE DIN RAIL	8
3.4	REMOVING THE MODULE FROM THE DIN RAIL	9
3.5	GROUNDING/SHIELDING	9
3.6	NETWORK TERMINATION	9
4.	SETTING THE NODE ID AND BAUD RATE	10
4.1	CHANGING THE DIP SWITCH TO SET THE NODE ID AND BAUD RATE	10
4.2	SETTING THE NODE ID USING THE DIP SWITCHES.....	11
4.3	SETTING THE BAUD RATE USING THE DIP SWITCHES	11
4.4	SETTING THE NODE ID USING SOFTWARE.....	11
4.5	SETTING THE BAUD RATE USING SOFTWARE	12
5.	WIRING	13
5.1	POWER SUPPLY AND COMMUNICATIONS WIRING	13
5.2	WIRING THE DIGITAL INPUTS AND OUTPUTS	14
6.	INDICATORS	15
6.1	FRONT PANEL INDICATORS	15
6.2	RUN INDICATOR (R)	16
6.3	ERROR INDICATOR (T).....	16
7.	IMPLEMENTED CANOPEN OBJECTS	17
7.1	OBJECT BLOCK DIAGRAMS.....	17
7.1.1	Block diagram for digital inputs	17
7.1.2	Block diagram for digital outputs	17
7.2	COMMUNICATION SEGMENT	18
7.2.1	Object 1000h: Device Type	18
7.2.2	Object 1001h: Error Register	18
7.2.3	Object 1003h: Pre-defined Error Field.....	19
7.2.4	Object 1005h: COB-ID SYNC.....	22
7.2.5	Object 1008h: Manufacturer Device Name	22
7.2.6	Object 1009h: Manufacturer Hardware Version	23
7.2.7	Object 100Ah: Manufacturer Software Version	23
7.2.8	Object 100Ch: Guard Time	24
7.2.9	Object 100Dh: Life Time Factor	24
7.2.10	Object 1010h: Store Parameter Field	25
7.2.11	Object 1011h: Restore Default Parameters.....	27
7.2.12	Object 1014h: COB-ID EMCY.....	28
7.2.13	Object 1015h: Inhibit Time Emergency	29
7.2.14	Object 1016h: Heartbeat Consumer Entries.....	29
7.2.15	Object 1017h: Producer Heartbeat Time.....	30
7.2.16	Object 1018h: Identity Object	31
7.2.17	Object 1029h: Error Behaviour	33
7.2.18	Object 1200h: Server SDO Parameter 1	34

7.2.19	Object 1400h: Receive PDO Communication Parameter 1	35
7.2.20	Object 1600h: Receive PDO Mapping Parameter 1	36
7.2.21	Object 1800h: Transmit PDO Communication Parameter 1	39
7.2.22	Object 1804h: Transmit PDO Communication Parameter 5	41
7.2.23	Object 1805h: Transmit PDO Communication Parameter 6	42
7.2.24	Object 1806h: Transmit PDO Communication Parameter 7	43
7.2.25	Object 1A00h: Transmit PDO Mapping Parameter 1	45
7.2.26	Object 1A04h: Transmit PDO Mapping Parameter 5	46
7.2.27	Object 1A05h: Transmit PDO Mapping Parameter 6	47
7.2.28	Object 1A06h: Transmit PDO Mapping Parameter 7	48
7.3	MANUFACTURER SEGMENT	50
7.3.1	Object 2001h: Module ID	50
7.3.2	Object 2002h: Module Baud Rate	50
7.3.3	Object 2003h: Module DIP Switch	51
7.3.4	Object 2100h: Input Filter Value	51
7.3.5	Object 2101h: Counter Filter Enable	52
7.3.6	Object 2150h: Counter Commands	52
7.3.7	Object 2200h: Counter Enable	53
7.3.8	Object 2201h: Counter Preload	53
7.3.9	Object 2202h: Counter Value	56
7.4	DEVICE PROFILE SEGMENT	58
7.4.1	Object 6000h: Read State 6 Input Lines	58
7.4.2	Object 6002h: Polarity 6 Input Lines	59
7.4.3	Object 6003h: Filter Constant 6 Input Lines	60
7.4.4	Object 6005h: Enable Digital Input Interrupts	60
7.4.5	Object 6007h: Input Interrupt Mask 6 - low to high	61
7.4.6	Object 6008h: Input Interrupt Mask 6 - high to low	62
7.4.7	Object 6020h: Read State 1 Input Line 1-6	63
7.4.8	Object 6200h: Write State 6 Output Lines	65
7.4.9	Object 6202h: Polarity 6 Output Lines	66
7.4.10	Object 6206h: Error Mode 6 Output Lines	67
7.4.11	Object 6207h: Fault State 6 Output Lines	68
7.4.12	Object 6220h: Write State 1 Output Line 1-6	69
8.	SAFETY GUIDELINES	71
8.1	INTRODUCTION	71
8.2	INTENDED USE	71
8.3	TRANSPORT AND STORAGE	71
8.4	INSTALLATION	71

1. Introduction

The PC6DIO module is a 6 channel digital input and 6 channel digital output module.

The inputs are isolated from the logic by opto-couplers and are designed to be switched to positive (common negative). The inputs have internal counters associated with them. These counters are 32 bit counters allowing a count value from 0 to 4294967295.

The 6 digital outputs are open drain MOSFET (N-TYPE). The outputs may be used to drive lamps or external relays when more drive capability is required. The outputs are isolated from the logic and they share a common negative terminal.

The module plugs into a special bus connector which fits inside the DIN rail. The power supply voltage and the CAN bus signals are connected via this bus connector.

The CAN interface is electrically isolated and is compliant with ISO 11898.

The module has **been equipped with status led's which are used to indicate** the status of the Inputs and communications. This visual indication assists with fault finding and diagnostics.

The CANopen node ID and bit rate can be setup by DIP switches or software.

2. Technical Specification

Power Supply	Logic Supply Voltage	12 -24 Vdc
	Logic Supply Current	37mA @ 12V / 21mA @ 24V
	Field Supply Voltage	12 -24 Vdc
	Field Supply Current	6mA @ 12V / 6mA @ 24V
Digital Inputs	Input Points	6
	Input Voltage Range	12 - 24 Vdc
	Input Current per input	2mA @ 12Vdc / 4mA @ 24Vdc
	Isolation	1500Vrms between field and logic
	Typical ON/OFF Delay	< 1ms with filter disabled
Counters	Inputs	1 to 6
	Resolution	32 Bits
	Frequency	5KHz (max)
	Pulse Width	100us (min)
Digital Outputs	Output Points	6
	Maximum Voltage	48 Vdc
	Maximum Current	0.5A per output
	On-state resistance	0.55 ohms
	Output update rate	< 1ms
	Isolation	1500Vrms between field and logic
CANopen Data	NMT	Slave
	Error Control	Node Guarding / Consumer Heartbeat
	Node ID	DIP switch or software
	Number of PDO	1Rx 4Tx
	PDO Modes	Event Controlled Asynchronous, Event Timer Asynchronous, Sync - Acyclic, Sync – Cyclic.
	PDO Mapping	Variable
	PDO Linking	Supported
	Number of SDO	1 Server
	Error Message	Yes
Temperature	Operating Temperature.	-20°C to + 70°C
	Storage Temperature	-40°C to + 85°C
Connectors	Logic Power and Comms.	5 way connector that clips onto DIN rail
	Inputs	6 x 3 Way screw connector on top and bottom

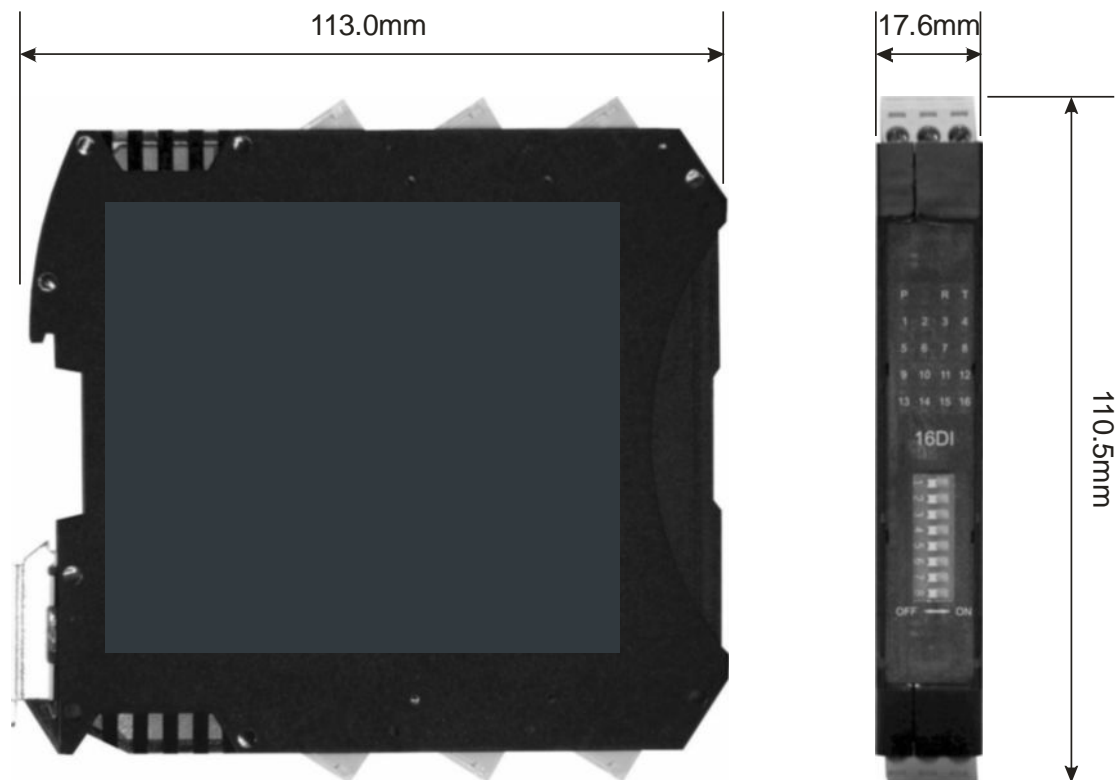
Note: Inputs 1 to 6 are used as both digital inputs and counter inputs.

3. Physical Information

3.1 Physical Dimensions

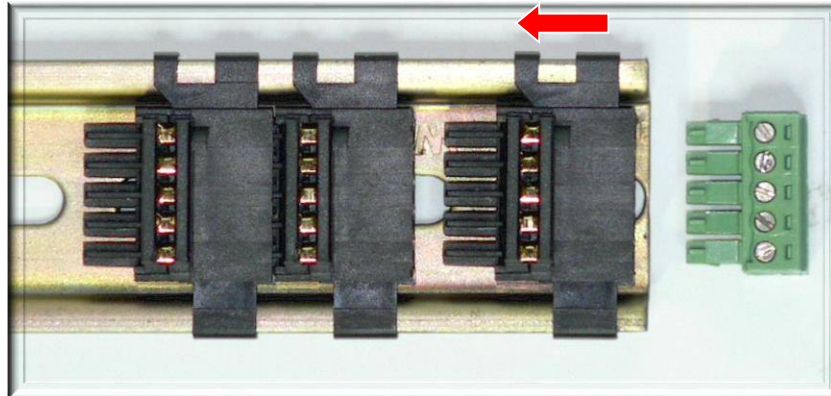
The PC6DIO enclosure is shown below. The module clips directly onto an industry standard DIN rail. Field wiring is on the top and bottom of the module via 6 plug-in connectors. The module power and CAN communications wiring is on a separate connector which clips onto the DIN rail on the back of the housing.

Allow at least 25mm on top and below the module to accommodate the wiring. Ensure that enough space is kept above and below the module for good ventilation.



3.2 DIN rail Bus adaptor

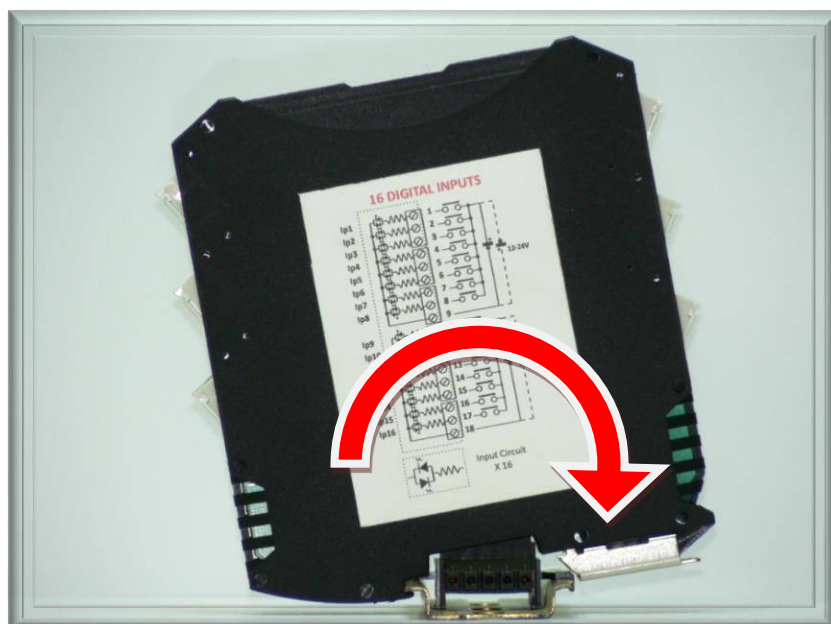
The BUS connector allows side-by-side installation of the Modules. The picture below shows multiple BUS connectors installed on a DIN rail. First, install the BUS connector onto the DIN rail, then slide into the adjacent BUS connector.



3.3 Installing the module onto the DIN rail

The modules are designed to be installed on a standard 35 mm DIN rail. Snap the BUS connector first into the rail as shown above. Next clip the top of the module onto the DIN rail and pivot the Module onto the DIN rail. The spring loaded clasp will latch around onto the DIN resulting in a firmly seated product. Do not force the module onto the connector otherwise the module or connector may be damaged.

Note: The modules are not designed for hot plug in. The power must be turned off before the modules are plugged into the base.



3.4 Removing the module from the DIN rail

To remove the module from the DIN Rail, use a flat blade screwdriver to pry the spring loaded clasp away from the DIN rail in the manner shown in the picture below. Next pivot the module up and away from the DIN rail and remove.



3.5 Grounding/Shielding

In most cases, the modules will be installed in an enclosure along with other devices which generate electromagnetic radiation. Examples of these devices are relays and contactors, transformers, motor controllers etc. This electromagnetic radiation can induce electrical noise into both power and signal lines, as well as direct radiation into the module causing negative effects on the system. Appropriate grounding, shielding and other protective steps should be taken at the installation stage to prevent these effects. These protective steps include control cabinet grounding, module grounding, cable shield grounding, protective elements for electromagnetic switching devices, correct wiring as well as consideration of cable types and their cross sections.

3.6 Network Termination

Transmission line effects often present a problem on data communication networks. These problems include reflections and signal attenuation.

To eliminate the presence of reflections from the end of the cable, the cable must be terminated at both ends with a resistor across the line equal to its characteristic impedance. Both ends must be terminated since the direction of propagation is bi-directional. This termination is typically 120 ohms.

4. Setting the Node ID and baud rate

The DIP switches are provided to manually configure the module node ID and baud rate. Switches 1 through 5 set the node ID sequentially starting at 1 and ending at 31. Switches 6, 7 & 8 set the baud rate. When the ID switches are all set to zero, the ID is taken from internal memory. When the baud rate switches are all set to zero, the baud rate is taken from the internal memory. The user must first configure the module by writing the correct values to the module.

4.1 Changing the DIP switch to set the Node ID and baud rate

The software in the module samples the dip switches on a reset when the power is cycled. Once sampled, the software writes the settings to the CAN port. The user is welcome to change the dip switches while the module is powered, however, a reset must be initiated afterward.

The DIP switch can be toggled using a small flat blade screwdriver, or equivalent tool, as shown in the picture below.



4.2 Setting the Node ID using the DIP switches

The following table assists with the setting up of DIP switches for the required NODE ID.

NODE ID	SWITCH SETTING							
	SW8	SW7	SW6	SW5	SW4	SW3	SW2	SW1
Software	-	-	-	Off	Off	Off	Off	Off
1	-	-	-	Off	Off	Off	Off	On
2	-	-	-	Off	Off	Off	On	Off
3	-	-	-	Off	Off	Off	On	On
4	-	-	-	Off	Off	On	Off	Off
4	-	-	-	Off	Off	On	Off	On
6	-	-	-	Off	Off	On	On	Off
-	-	-	-	-	-	-	-	-
31	-	-	-	On	On	On	On	On

4.3 Setting the Baud Rate using the DIP switches

The following table assists with the setting up of DIP switches for the required Baud Rate.

BAUD RATE	SWITCH SETTING							
	SW8	SW7	SW6	SW5	SW4	SW3	SW2	SW1
kbits/s	SW8	SW7	SW6	SW5	SW4	SW3	SW2	SW1
Software	Off	Off	Off					
20	Off	Off	On	-	-	-	-	-
50	Off	On	Off	-	-	-	-	-
125	Off	On	On	-	-	-	-	-
250	On	Off	Off	-	-	-	-	-
500	On	Off	On	-	-	-	-	-
800	On	On	Off	-	-	-	-	-
1000	On	On	On	-	-	-	-	-

4.4 Setting the Node ID using software.

In order to use the node ID from memory, ensure that all of the node ID dip switches are in the OFF position.

Before the internal node id is selected, the user must first write the correct id value to the Module ID object in the manufacturer segment. The object address is 2001h.

The node id can be configured from 1 to 127.

4.5 Setting the baud rate using software.

In order to use the baud rate from memory, ensure that all of the baud rate dip switches are in the OFF position.

Before the internal baud rate is selected, the user must first write the correct baud rate value to the Module Baud Rate object in the manufacturer segment. The object address is 2002h.

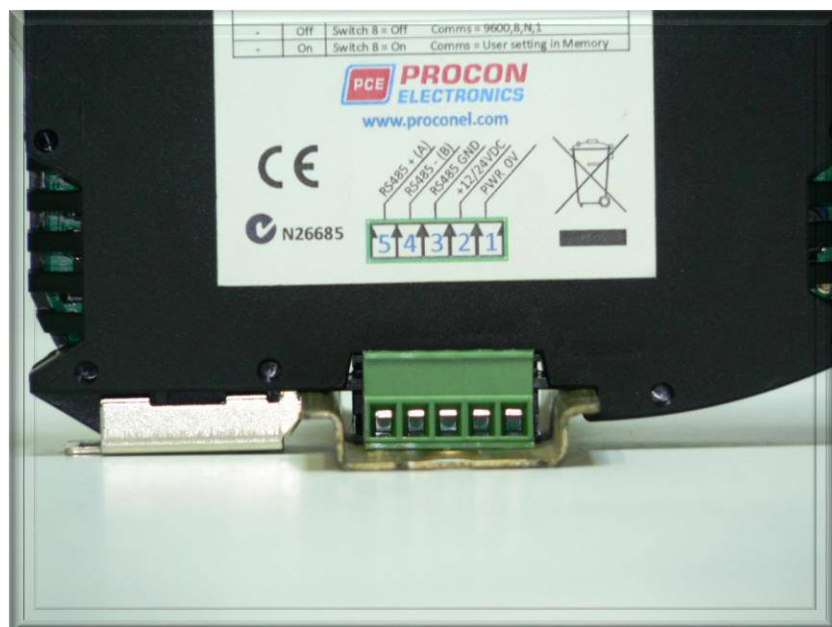
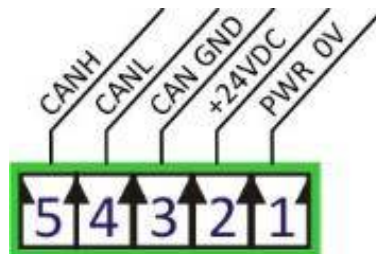
The following baud rates are supported.

BAUD RATE	OBJECT VALUE (2002h)
kbits/s	
20	1
50	2
100	3
125	4
250	5
500	6
800	7
1000	8

5. Wiring

5.1 Power supply and Communications Wiring

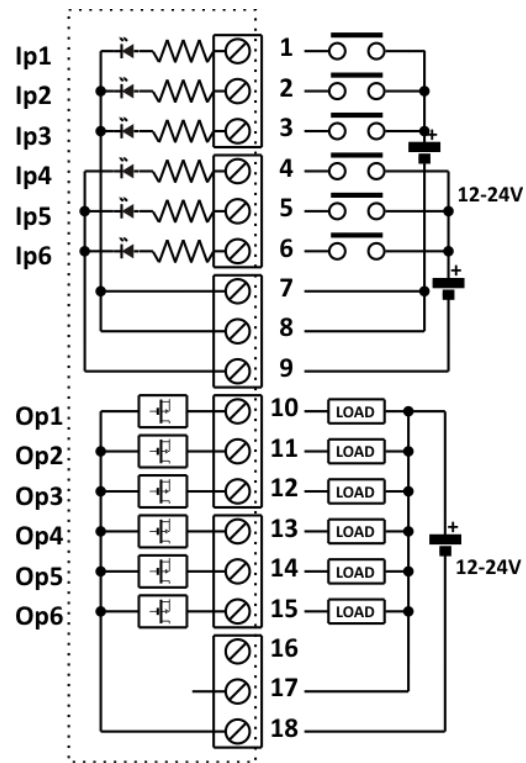
The following diagram shows the wiring for the power and CAN communications.



Terminal		Description
1	Power 0V	The DC power supply 0V connection.
2	Power +24V	The DC power supply positive connection. 12V to 24VDC.
3	CAN GND	The CAN circuit is isolated from the DC power supply for the module. The CAN GND connection is not connected to the DC power supply GND. Use a separate ground wire to connect all of the CAN GND terminals on the modules together. This ensures that all of the modules are at the same potential. The ground wire must be earthed at one end only.
4	CANL	CANL network connection
5	CANH	CANH network connection

5.2 Wiring the digital inputs and outputs

The following diagram shows how the digital inputs and outputs are connected.



6. Indicators

6.1 Front panel indicators

The CAN communications uses an error LED (T) and a run LED (R). The run LED indicates the CANopen state. The error LED is shows errors of the network.

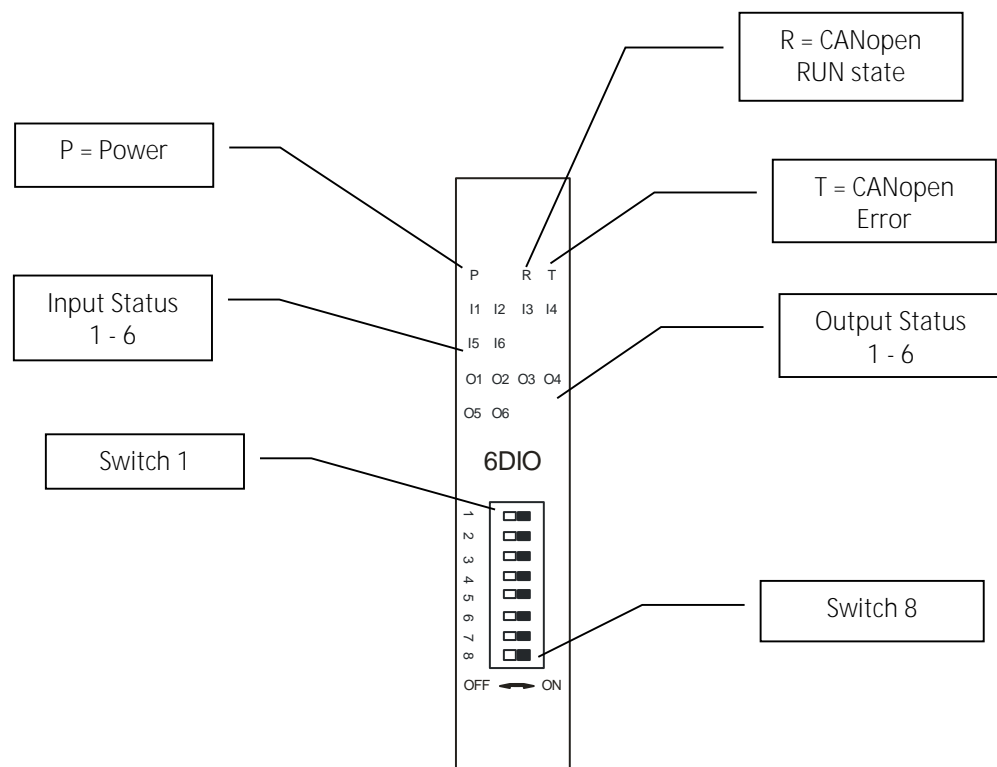
Power: Flashes to indicate the CPU is running.

CAN (R): Indicates the CANopen run state.

CAN (T): Indicates a CANopen error.

Input Status: **"OFF" when the input is off**
"ON" when the input is on.

Output Status: **"OFF" when the output is off**
"ON" when the output is on.



6.2 Run indicator (R)

RUN LED	State	Description
Single flash	STOPPED	The device is in STOPPED state.
Blinking	PRE-OPERATIONAL	The device is in PRE- OPERATIONAL state.
On	RUN	The device is in RUN state.

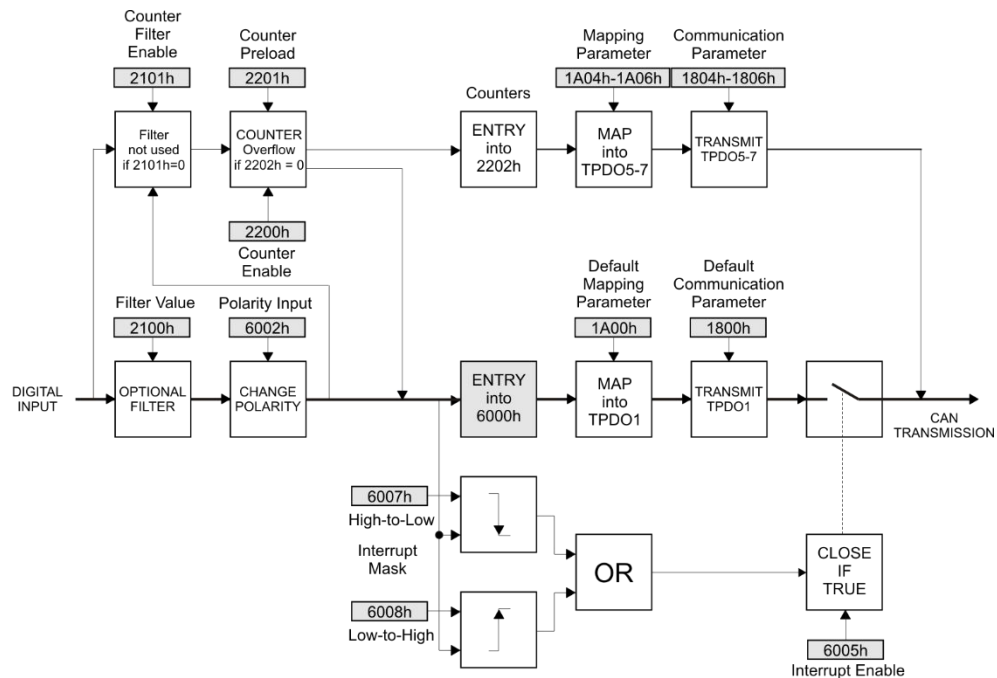
6.3 Error indicator (T)

ERROR LED	State	Description
Off	no error	The device is in working condition.
Single flash	warning limit reached	At least one of the error counters of the CAN controller has reached or exceeded the warning limit.
Double flash	Error Control Event	A guard event (NMT- Slave or NMT- Master) or a Heartbeat event has occurred.
On	Bus Off	The CAN controller is bus-off.

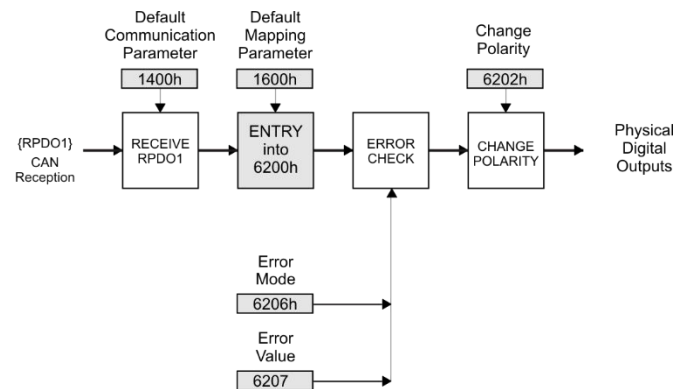
7. Implemented CANopen Objects

7.1 Object Block Diagrams

7.1.1 Block diagram for digital inputs



7.1.2 Block diagram for digital outputs



7.2 Communication Segment

7.2.1 Object 1000h: Device Type

The device type specifies the kind of device. The lower 16 bit contain the device profile number and the upper 16 bit an additional information.

INDEX	1000
Name	Device Type
Object Code	Variable
Data Type	UNSIGNED32
Access	CONST
PDO Mapping	No
Default Value	0x00030191

7.2.2 Object 1001h: Error Register

The error register is a field of 8 bits, each for a certain error type. If an error occurs the bit has to be set.

Bit	Meaning
0	generic error
1	-
2	-
3	-
4	communication error (overflow, error state)
5	-
6	-
7	-

INDEX	1001
Name	Error Register
Object Code	Variable
Data Type	UNSIGNED8
Access	RO
PDO Mapping	No
Default Value	0x00

7.2.3 Object 1003h: Pre-defined Error Field

This object holds errors that have occurred on the device and have been signalled via Emergency Object. It is an error history.

Writing to sub index 0 deletes the entire error history.

ERROR	CODE
Communications Error	0x8100
CAN Overrun Error	0x8110
CAN in error passive	0x8120
Heart Beat or life guard error	0x8130
CAN recovered from bus-off	0x8140
PDO not processed due the length	0x8210
PDO length exceeded	0x8220

INDEX	1003
Name	Pre-defined Error Field
Object Code	Array
Data Type	UNSIGNED32

Sub-Index	000
Description	Number of Errors
Access	RW
PDO Mapping	No
Default Value	0x00000000
Sub-Index	001
Description	Standard Error Field
Data Type	UNSIGNED32
Access	RO
PDO Mapping	No
Default Value	0x00000000
Sub-Index	002
Description	Standard Error Field
Data Type	UNSIGNED32

Access	RO
PDO Mapping	No
Default Value	0x00000000
Sub-Index	003
Description	Standard Error Field
Data Type	UNSIGNED32
Access	RO
PDO Mapping	No
Default Value	0x00000000
Sub-Index	004
Description	Standard Error Field
Data Type	UNSIGNED32
Access	RO
PDO Mapping	No
Default Value	0x00000000
Sub-Index	005
Description	Standard Error Field
Data Type	UNSIGNED32
Access	RO
PDO Mapping	No
Default Value	0x00000000
Sub-Index	006
Description	Standard Error Field
Data Type	UNSIGNED32
Access	RO
PDO Mapping	No

Default Value	0x00000000
Sub-Index	007
Description	Standard Error Field
Data Type	UNSIGNED32
Access	RO
PDO Mapping	No
Default Value	0x00000000
Sub-Index	008
Description	Standard Error Field
Data Type	UNSIGNED32
Access	RO
PDO Mapping	No
Default Value	0x00000000
Sub-Index	009
Description	Standard Error Field
Data Type	UNSIGNED32
Access	RO
PDO Mapping	No
Default Value	0x00000000
Sub-Index	010
Description	Standard Error Field
Data Type	UNSIGNED32
Access	RO
PDO Mapping	No
Default Value	0x00000000

7.2.4 Object 1005h: COB-ID SYNC

COB-ID of the Synchronization object.

The device generates a SYNC message if bit 30 is set.

The meaning of other bits is equal to the other communication objects.

INDEX	1005
Name	COB-ID SYNC
Object Code	Variable
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x00000080

7.2.5 Object 1008h: Manufacturer Device Name

Contains the device name.

INDEX	1008
Name	Manufacturer Device Name
Object Code	Variable
Data Type	VISIBLE_STRING
Access	CONST
PDO Mapping	No
Default Value	PC6DIO

7.2.6 Object 1009h: Manufacturer Hardware Version

Contains the device hardware version.

INDEX	1009
Name	Manufacturer Hardware Version
Object Code	Variable
Data Type	VISIBLE_STRING
Access	CONST
PDO Mapping	No
Default Value	V01.00

7.2.7 Object 100Ah: Manufacturer Software Version

Contains the device software version.

INDEX	100A
Name	Manufacturer Software Version
Object Code	Variable
Data Type	VISIBLE_STRING
Access	CONST
PDO Mapping	No
Default Value	V01.00

7.2.8 Object 100Ch: Guard Time

This entry contains the guard time in milli-seconds.
It is 0, if not used.

INDEX	100C
Name	Guard Time
Object Code	Variable
Data Type	UNSIGNED16
Access	RW
PDO Mapping	No
Default Value	0x00000000
Unit	ms

7.2.9 Object 100Dh: Life Time Factor

The life time factor multiplied with the guard time gives the life time for the device.
It is 0, if not used.

INDEX	100D
Name	Life Time Factor
Object Code	Variable
Data Type	UNSIGNED8
Access	RW
PDO Mapping	No
Default Value	0x00000000

7.2.10 Object 1010h: Store Parameter Field

This entry supports saving of parameters in non-volatile memory.

With a read access the device provides information about its saving capabilities. Several parameter groups are distinguished.

Sub index 1 : all parameters
Sub index 2 : communication parameters
Sub index 3 : application parameters
Sub index 4 - 127: manufacturer defined parameters

For saving the signature "save" (0x65766173) must be written.

The following parameters can be saved or loaded:

Communication Parameter	Object
COB-ID SYNC	1005h
Guard Time	100Ch
Life Time Factor	100Dh
COB-ID EMCY	1014h
Heartbeat Consumer Entries	1016h
Producer Heartbeat Time	1017h
PDO length exceeded	1029h
Manufacturer Specific Parameter	Object
Module ID	2001h
Module Baud Rate	2002h
Input Filter Value	2100h
Counter Filter Enable	2101h
Application Parameter	Object
Polarity 6 Input Lines	6002h
Filter Constant 6 Input Lines	6003h
Enable Digital Input Interrupts	6005h
Input Interrupt Mask 6 - low to high	6007h
Input Interrupt Mask 6 - high to low	6008h
Polarity 6 Output Lines	6202h
Error Mode 6 Output Lines	6206h
Fault State 6 Output Lines	6207h

INDEX	1010
Name	Store Parameter Field
Object Code	Array
Data Type	UNSIGNED32
Sub-Index	000
Description	Number of Entries
Access	RO
PDO Mapping	No

Default Value	0x4
---------------	-----

Sub-Index	001
Description	Save all Parameters
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x00000000

Sub-Index	002
Description	Save Communication Parameters
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x00000000

Sub-Index	003
Description	Save Application Parameters
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x00000000

Sub-Index	004
Description	Save Manufacturers Parameters
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x00000000

7.2.11 Object 1011h: Restore Default Parameters

This entry supports restoring of default parameters.

With a read access the device provides information about its capabilities to restore these values. Several parameter groups are distinguished.

Sub index 1 : all parameters
Sub index 2 : communication parameters
Sub index 3 : application parameters
Sub index 4 - 127: manufacturer defined parameters

For restoring the signature "load" (0x646166c) must be written.

INDEX	1011
Name	Restore Default Parameters
Object Code	Array
Data Type	UNSIGNED32

Sub-Index	000
Description	Number of Entries
Access	RO
PDO Mapping	No
Default Value	0x4
Sub-Index	001
Description	Restore all Default Parameters
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x00000000
Sub-Index	002
Description	Restore Communication Default Parameters
Data Type	UNSIGNED32
Access	RW

PDO Mapping	No
Default Value	0x00000000
Sub-Index	003
Description	Restore Application Default Parameters
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x00000000
Sub-Index	004
Description	Restore Manufacturers Default Parameters
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x00000000

7.2.12 Object 1014h: COB-ID EMCY

COB-ID used for emergency message (Emergency Producer).

INDEX	1014
Name	COB-ID EMCY
Object Code	Variable
Data Type	UNSIGNED32
Access	RO
PDO Mapping	No
Default Value	0x00000080

7.2.13 Object 1015h: Inhibit Time Emergency

Inhibit Time used for emergency message (Emergency Producer).
The time has to be a multiple of 100 us.

INDEX	1015
Name	Inhibit Time Emergency
Object Code	Variable
Data Type	UNSIGNED16
Access	RW
PDO Mapping	No
Default Value	0x0

7.2.14 Object 1016h: Heartbeat Consumer Entries

The consumer heartbeat time defines the expected heartbeat cycle time and thus has to be higher than the corresponding producer heartbeat time configured on the device producing this heartbeat.

The bits 31 - 24 of each sub-index has to be 0.

The bits 23 - 16 contain the node-id.

The lower 16 bits contain the heartbeat time

INDEX	1016
Name	Heartbeat Consumer Entries
Object Code	Array
Data Type	UNSIGNED32

Sub-Index	000
Description	Number of Entries
Access	RO
PDO Mapping	No
Default Value	0x02
Sub-Index	001
Description	Consumer Heartbeat Time 1
Data Type	UNSIGNED32

Access	RW
PDO Mapping	No
Default Value	0x00000000
Sub-Index	002
Description	Consumer Heartbeat Time 2
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x00000000

7.2.15 Object 1017h: Producer Heartbeat Time

The producer heartbeat time defines the cycle time of the heartbeat. If the time is 0 it is not used. The time has to be a multiple of 1 msec

INDEX	1017
Name	Producer Heartbeat Time
Object Code	Variable
Data Type	UNSIGNED16
Access	RW
PDO Mapping	No
Default Value	0x00000000

7.2.16 Object 1018h: Identity Object

This object contains general information about the device.

Sub-Index 1 contains a unique value allocated each manufacturer.

Sub-Index 2 identifies the manufacturer specific product code (device version).

Sub-Index 3 contains the revision number. Bit 31-16 is the major revision number and Bit 15-0 the minor revision number.

Sub-Index 4 identified a manufacturer specific serial number.

INDEX	1018
Name	Identity Object
Object Code	Record
Data Type	IDENTITY

Sub-Index	000
Description	number of entries
Access	RO
PDO Mapping	No
Default Value	0x4
Sub-Index	001
Description	Vendor Id
Data Type	UNSIGNED32
Access	RO
PDO Mapping	No
Default Value	0x000003AD
Sub-Index	002
Description	Product Code
Data Type	UNSIGNED32
Access	RO
PDO Mapping	No
Default Value	0x0

Sub-Index	003
Description	Revision number
Data Type	UNSIGNED32
Access	RO
PDO Mapping	No
Default Value	0x0
Sub-Index	004
Description	Serial number
Data Type	UNSIGNED32
Access	RO
PDO Mapping	No
Default Value	0

7.2.17 Object 1029h: Error Behaviour

Sub index 000 contains the number of error classes.

Sub index 001 contains the error class for a communication error.

Sub indices 001 to 254 contain device profile or manufacturer specific error classes.

The value of an error class can be:

0 = pre - operational

1 = no state change

2 = stopped

3 .. 127 reserved

INDEX	1029
Name	Error Behaviour
Object Code	Array
Data Type	UNSIGNED8

Sub-Index	000
Description	Number of Entries
Access	RO
PDO Mapping	No
Default Value	1
Sub-Index	001
Description	Communication Error
Data Type	UNSIGNED8
Access	RW
PDO Mapping	No
Default Value	0x0

7.2.18 Object 1200h: Server SDO Parameter 1

The object contains the parameters for the SDOs for which the device is the server.

INDEX	1200
Name	Server SDO Parameter 1
Object Code	Record
Data Type	SDO_PARAMETER

Sub-Index	000
Description	Number of Entries
Access	RO
PDO Mapping	No
Default Value	2
Sub-Index	001
Description	COB-ID Client -> Server
Data Type	UNSIGNED32
Access	RO
PDO Mapping	No
Default Value	0x00000600
Sub-Index	002
Description	COB-ID Server -> Client
Data Type	UNSIGNED32
Access	RO
PDO Mapping	No
Default Value	0x00000580

7.2.19 Object 1400h: Receive PDO Communication Parameter 1

It contains the communication parameters of the current PDO the device is able to receive.

Sub-index 0 contains the number of PDO-parameters implemented.

Sub index 1 describes the COB-ID. If bit 31 is set the PDO is disabled.

The transmission mode is defined by sub-index 2.

An inhibit time can be defined on sub-index 3 in 100 us.

At the 5th sub-index can be defined an event time for asynchronous pdos.

INDEX	1400
Name	Receive PDO Communication Parameter 1
Object Code	Record
Data Type	PDO_COMM_PAR

Sub-Index	000
Description	Number of Entries
Access	RO
PDO Mapping	No
Default Value	0x03
Sub-Index	001
Description	COB-ID
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x00000200
Sub-Index	002
Description	Transmission Type
Data Type	UNSIGNED8
Access	RW
PDO Mapping	No
Default Value	0xFF

Sub-Index	003
Description	Inhibit Time
Data Type	UNSIGNED16
Access	RW
PDO Mapping	No
Default Value	0x0
Unit	100 us

7.2.20 Object 1600h: Receive PDO Mapping Parameter 1

The sub-indices contain the indices, the sub-indices and the lengths of the mapped sub-indices.

Their structure is as follows:

index (16bit) sub-index (8bit) length (8bit)

INDEX	1600
Name	Receive PDO Mapping Parameter 1
Object Code	Record
Data Type	PDO_MAPPING

Sub-Index	000
Description	Number of Entries
Access	RW
PDO Mapping	No
Default Value	0x01
Sub-Index	001
Description	Mapping Entry 1
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x62000108

Sub-Index	002
Description	Mapping Entry 2
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x00050008
Sub-Index	003
Description	Mapping Entry 3
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x00050008
Sub-Index	004
Description	Mapping Entry 4
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x00050008
Sub-Index	005
Description	Mapping Entry 5
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x00050008
Sub-Index	006
Description	Mapping Entry 6

Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x00050008
Sub-Index	007
Description	Mapping Entry 7
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x00050008
Sub-Index	008
Description	Mapping Entry 8
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x00050008

7.2.21 Object 1800h: Transmit PDO Communication Parameter 1

It contains the communication parameters of the current PDO the device is able to transmit.

Sub-index 0 contains the number of PDO-parameters implemented.

Sub index 1 describes the COB-ID. If bit 31 is set the PDO is disabled.

The transmission mode is defined by sub-index 2.

An inhibit time can be defined on sub-index 3 in 100 us.

At the 5th sub-index can be defined an event time for asynchronous pdos.

INDEX	1800
Name	Transmit PDO Communication Parameter 1
Object Code	Record
Data Type	PDO_COMM_PAR
Sub-Index	000
Description	Number of Entries
Access	RO
PDO Mapping	No
Default Value	0x05
Sub-Index	001
Description	COB-ID
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x00000180
Sub-Index	002
Description	Transmission Type
Data Type	UNSIGNED8
Access	RW
PDO Mapping	No
Default Value	0xFF
Sub-Index	003

Description	Inhibit Time
Data Type	UNSIGNED16
Access	RW
PDO Mapping	No
Default Value	0x0
Unit	100 us
Sub-Index	004
Description	Compatibility Entry
Data Type	UNSIGNED8
Access	RW
PDO Mapping	No
Default Value	0x00
Sub-Index	005
Description	Event Timer
Data Type	UNSIGNED16
Access	RW
PDO Mapping	No
Default Value	0x0
Unit	ms

7.2.22 Object 1804h: Transmit PDO Communication Parameter 5

It contains the communication parameters of the current PDO the device is able to transmit.

Sub-index 0 contains the number of PDO-parameters implemented.

Sub index 1 describes the COB-ID. If bit 31 is set the PDO is disabled.

The transmission mode is defined by sub-index 2.

An inhibit time can be defined on sub-index 3 in 100 us.

At the 5th sub-index can be defined an event time for asynchron pdos.

INDEX	1804
Name	Transmit PDO Communication Parameter 5
Object Code	Record
Data Type	PDO_COMM_PAR

Sub-Index	000
Description	Number of Entries
Access	RO
PDO Mapping	No
Default Value	0x03
Sub-Index	001
Description	COB-ID
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x80000180
Sub-Index	002
Description	Transmission Type
Data Type	UNSIGNED8
Access	RW
PDO Mapping	No
Default Value	0x1
Sub-Index	003

Description	Inhibit Time
Data Type	UNSIGNED16
Access	RW
PDO Mapping	No
Default Value	0x0
Unit	100 us

7.2.23 Object 1805h: Transmit PDO Communication Parameter 6

It contains the communication parameters of the current PDO the device is able to transmit.

Sub-index 0 contains the number of PDO-parameters implemented.

Sub index 1 describes the COB-ID. If bit 31 is set the PDO is disabled.

The transmission mode is defined by sub-index 2.

An inhibit time can be defined on sub-index 3 in 100 us.

At the 5th sub-index can be defined an event time for asynchron pdos.

INDEX	1805
Name	Transmit PDO Communication Parameter 6
Object Code	Record
Data Type	PDO_COMM_PAR
Sub-Index	000
Description	Number of Entries
Access	RO
PDO Mapping	No
Default Value	0x03
Sub-Index	001
Description	COB-ID
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x80000180

Sub-Index	002
Description	Transmission Type
Data Type	UNSIGNED8
Access	RW
PDO Mapping	No
Default Value	0x1
Sub-Index	003
Description	Inhibit Time
Data Type	UNSIGNED16
Access	RW
PDO Mapping	No
Default Value	0x0
Unit	100 us

7.2.24 Object 1806h: Transmit PDO Communication Parameter 7

It contains the communication parameters of the current PDO the device is able to transmit.

Sub-index 0 contains the number of PDO-parameters implemented.

Sub index 1 describes the COB-ID. If bit 31 is set the PDO is disabled.

The transmission mode is defined by sub-index 2.

An inhibit time can be defined on sub-index 3 in 100 us.

At the 5th sub-index can be defined an event time for asynchron pdos.

INDEX	1806
Name	Transmit PDO Communication Parameter 7
Object Code	Record
Data Type	PDO_COMM_PAR
Sub-Index	000
Description	Number of Entries
Access	RO
PDO Mapping	No

Default Value	0x03
Sub-Index	001
Description	COB-ID
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x80000180
Sub-Index	002
Description	Transmission Type
Data Type	UNSIGNED8
Access	RW
PDO Mapping	No
Default Value	0x1
Sub-Index	003
Description	Inhibit Time
Data Type	UNSIGNED16
Access	RW
PDO Mapping	No
Default Value	0x0
Unit	100 us

7.2.25 Object 1A00h: Transmit PDO Mapping Parameter 1

Contains the mapping for the PDOs the device is able to transmit.

The type of the PDO mapping parameter is at index 21h.

The subindex 0h contains the number of valid entries within the mapping record.

This number of entries is also the number of the application variables which shall be transmitted with the corresponding PDO.

The subindices from 1h to number of entries contain the information about the mapped application variables.

These entries describe the PDO contents by their index, subindex and length.

All three values are hexa-decimal coded.

The length entry contains the length of the object in bits (1..40h).

This parameter can be used to verify the overall mapping length. It is mandatory.

INDEX	1A00
Name	Transmit PDO Mapping Parameter 1
Object Code	Record
Data Type	PDO_MAPPING
Sub-Index	000
Description	Number of Entries
Access	RW
PDO Mapping	No
Default Value	0x02
Sub-Index	001
Description	Mapping Entry 1
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x60000108
Sub-Index	002
Description	Mapping Entry 2
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No

Default Value	0x60000208
---------------	------------

7.2.26 Object 1A04h: Transmit PDO Mapping Parameter 5

Contains the mapping for the PDOs the device is able to transmit.

The type of the PDO mapping parameter is at index 21h.

The subindex 0h contains the number of valid entries within the mapping record.

This number of entries is also the number of the application variables which shall be transmitted with the corresponding PDO.

The subindices from 1h to number of entries contain the information about the mapped application variables.

These entries describe the PDO contents by their index, subindex and length.

All three values are hexa-decimal coded.

The length entry contains the length of the object in bits (1..40h).

This parameter can be used to verify the overall mapping length.

It is mandatory.

INDEX	1A04
Name	Transmit PDO Mapping Parameter 5
Object Code	Record
Data Type	PDO_MAPPING
Sub-Index	000
Description	Number of Entries
Access	RW
PDO Mapping	No
Default Value	0x02
Sub-Index	001
Description	Mapping Entry 1
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x22020120
Sub-Index	002
Description	Mapping Entry 2
Data Type	UNSIGNED32

Access	RW
PDO Mapping	No
Default Value	0x22020220

7.2.27 Object 1A05h: Transmit PDO Mapping Parameter 6

Contains the mapping for the PDOs the device is able to transmit.

The type of the PDO mapping parameter is at index 21h.

The subindex 0h contains the number of valid entries within the mapping record.

This number of entries is also the number of the application variables which shall be transmitted with the corresponding PDO.

The subindices from 1h to number of entries contain the information about the mapped application variables.

These entries describe the PDO contents by their index, subindex and length.

All three values are hexa-decimal coded.

The length entry contains the length of the object in bits (1..40h).

This parameter can be used to verify the overall mapping length.

It is mandatory.

INDEX	1A05
Name	Transmit PDO Mapping Parameter 6
Object Code	Record
Data Type	PDO_MAPPING
Sub-Index	000
Description	Number of Entries
Access	RW
PDO Mapping	No
Default Value	0x02
Sub-Index	001
Description	Mapping Entry 1
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x22020320

Sub-Index	002
Description	Mapping Entry 2
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x22020420

7.2.28 Object 1A06h: Transmit PDO Mapping Parameter 7

Contains the mapping for the PDOs the device is able to transmit.

The type of the PDO mapping parameter is at index 21h.

The subindex 0h contains the number of valid entries within the mapping record.

This number of entries is also the number of the application variables which shall be transmitted with the corresponding PDO.

The subindices from 1h to number of entries contain the information about the mapped application variables.

These entries describe the PDO contents by their index, subindex and length.

All three values are hexa-decimal coded.

The length entry contains the length of the object in bits (1..40h).

This parameter can be used to verify the overall mapping length.

It is mandatory.

INDEX	1A06
Name	Transmit PDO Mapping Parameter 7
Object Code	Record
Data Type	PDO_MAPPING
Sub-Index	000
Description	Number of Entries
Access	RW
PDO Mapping	No
Default Value	0x02
Sub-Index	001
Description	Mapping Entry 1
Data Type	UNSIGNED32

Access	RW
PDO Mapping	No
Default Value	0x22020520
Sub-Index	002
Description	Mapping Entry 2
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x22020620

7.3 Manufacturer Segment

7.3.1 Object 2001h: Module ID

INDEX	2001
Name	Module ID
Object Code	Variable
Data Type	UNSIGNED8
Access	RW
PDO Mapping	No
Default Value	0x7F

7.3.2 Object 2002h: Module Baud Rate

INDEX	2002
Name	Module Baud Rate
Object Code	Variable
Data Type	UNSIGNED8
Access	RW
PDO Mapping	No
Default Value	0x04

7.3.3 Object 2003h: Module DIP Switch

INDEX	2003
Name	Module DIP Switch
Object Code	Variable
Data Type	UNSIGNED8
Access	RO
PDO Mapping	No
Default Value	0x00

7.3.4 Object 2100h: Input Filter Value

This parameter is configured to set the filter value for the inputs.

Each input has a filter counter. The input is sampled every 100uS.

When the input goes from a low level to a high level the counter increments. When the counter reaches the Filter Value threshold the input state changes from 0 to 1.

When the input goes from a high level to a low level the counter decrements. When the counter reaches the ZERO threshold the input state changes from 1 to 0.

INDEX	2100
Name	Input Filter Value
Object Code	Variable
Data Type	UNSIGNED16
Access	RW
PDO Mapping	No
Default Value	0x00

7.3.5 Object 2101h: Counter Filter Enable

The Counter filter enable object is used to determine if the counters for inputs 1-6 are connected to the input before or after the filter.

If the Counter filter enable object is set to 0, then the counters are connected directly to the inputs. The inputs are sampled every 100uS.

If the Counter filter enable object is set to 1, then the counters are connected to the inputs after the filter. The inputs are sampled every 200uS.

INDEX	2101
Name	Counter Filter Enable
Object Code	Variable
Data Type	UNSIGNED8
Access	RW
PDO Mapping	No
Default Value	0x00

7.3.6 Object 2150h: Counter Commands

The following commands can be written to the module relating to the input counters.

Preset Counter – 0x110n:

Preset the counter with the Counter Preload value in object 2201h. The variable n represents the counters to be preset. Bit0 = counter1, Bit1 = counter2, etc.

Clear Counter Overflow – 0x120n:

Clear the counter overflow bit in object 6000h3. The variable n represents the counters overflow bits to be cleared. Bit0 = overflow1, Bit1 = overflow2, etc.

INDEX	2150
Name	Counter Commands
Object Code	Variable
Data Type	UNSIGNED16
Access	RW
PDO Mapping	No
Default Value	0x00

7.3.7 Object 2200h: Counter Enable

This object is used to select which counters are enabled.
Bit0 = counter1, Bit1 = counter2, etc.

INDEX	2200
Name	Counter Enable
Object Code	Variable
Data Type	UNSIGNED8
Access	RW
PDO Mapping	No
Default Value	0x00

7.3.8 Object 2201h: Counter Preload

INDEX	2201
Name	Counter Preload
Object Code	Array
Data Type	UNSIGNED32
Sub-Index	000
Description	Number of Elements
Access	RO
PDO Mapping	No
Default Value	0x6
Sub-Index	001
Description	Counter Preload 1
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x0

Sub-Index	002
Description	Counter Preload 2
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x0
Sub-Index	003
Description	Counter Preload 3
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x0
Sub-Index	004
Description	Counter Preload 4
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x0
Sub-Index	005
Description	Counter Preload 5
Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x0
Sub-Index	006
Description	Counter Preload 6

Data Type	UNSIGNED32
Access	RW
PDO Mapping	No
Default Value	0x0

7.3.9 Object 2202h: Counter Value

INDEX	2202
Name	Counter Value
Object Code	Array
Data Type	UNSIGNED32
Sub-Index	000
Description	Number of Elements
Access	RO
PDO Mapping	No
Default Value	0x6
Sub-Index	001
Description	Counter Value 1
Data Type	UNSIGNED32
Access	RW
PDO Mapping	Yes
Default Value	0x0
Sub-Index	002
Description	Counter Value 2
Data Type	UNSIGNED32
Access	RW
PDO Mapping	Yes
Default Value	0x0
Sub-Index	003
Description	Counter Value 3
Data Type	UNSIGNED32
Access	RW

PDO Mapping	Yes
Default Value	0x0
Sub-Index	004
Description	Counter Value 4
Data Type	UNSIGNED32
Access	RW
PDO Mapping	Yes
Default Value	0x0
Sub-Index	005
Description	Counter Value 5
Data Type	UNSIGNED32
Access	RW
PDO Mapping	Yes
Default Value	0x0
Sub-Index	006
Description	Counter Value 6
Data Type	UNSIGNED32
Access	RW
PDO Mapping	Yes
Default Value	0x0

7.4 Device Profile Segment

7.4.1 Object 6000h: Read State 6 Input Lines

Reads a group of 8 input lines as a byte of information.

INDEX	6000
Name	Read State 6 Input Lines
Object Code	Array
Data Type	UNSIGNED8
Sub-Index	000
Description	Number of Elements
Access	RO
PDO Mapping	No
Default Value	0x2
Sub-Index	001
Description	digital Inputs 1-6
Data Type	UNSIGNED8
Access	RO
PDO Mapping	Yes
Default Value	0x00
Sub-Index	002
Description	Counter Overflow 1-6
Data Type	UNSIGNED8
Access	RO
PDO Mapping	Yes
Default Value	0x00

7.4.2 Object 6002h: Polarity 6 Input Lines

Defines the polarity of a group of 8 input lines.

INDEX	6002
Name	Polarity 6 Input Lines
Object Code	Array
Data Type	UNSIGNED8
Sub-Index	000
Description	Number of Elements
Access	RO
PDO Mapping	No
Default Value	0x1
Sub-Index	001
Description	Polarity for digital Inputs 1-6
Data Type	UNSIGNED8
Access	RW
PDO Mapping	No
Default Value	0x00

7.4.3 Object 6003h: Filter Constant 6 Input Lines

Filter constant for input modules. This defines that an additional configurable filter constant can be enabled or disabled.

INDEX	6003
Name	Filter Constant 6 Input Lines
Object Code	Array
Data Type	UNSIGNED8
Sub-Index	000
Description	Number of Elements
Access	RO
PDO Mapping	No
Default Value	0x1
Sub-Index	001
Description	Enable Filter for digital Inputs 1-6
Data Type	UNSIGNED8
Access	RW
PDO Mapping	No
Default Value	0x0

7.4.4 Object 6005h: Enable Digital Input Interrupts

Globally enable or disable input interrupts.

INDEX	6005
Name	Enable Digital Input Interrupts
Object Code	Variable
Data Type	BOOLEAN
Access	RW
PDO Mapping	No
Default Value	1

7.4.5 Object 6007h: Input Interrupt Mask 6 - low to high

Determines which input port lines activate an interrupt. Done for Groups of 8 lines and for a change from low to high of a digital input line.

The values are in OR connection to the values of object 6006H.

INDEX	6007
Name	Input Interrupt Mask 6 - low to high
Object Code	Array
Data Type	UNSIGNED8
Sub-Index	000
Description	Number of Elements
Access	RO
PDO Mapping	No
Default Value	0x2
Sub-Index	001
Description	Input Interrupt Mask low to high for digital Inputs 1-6
Data Type	UNSIGNED8
Access	RW
PDO Mapping	No
Default Value	0x00
Sub-Index	003
Description	Counter Overflow Interrupt Mask for counters 1-6
Data Type	UNSIGNED8
Access	RW
PDO Mapping	No
Default Value	0x00

7.4.6 Object 6008h: Input Interrupt Mask 6 - high to low

Determines which input port lines activate an interrupt.

Done for groups of 8 lines and for a change from high to low of a digital input line.

The values are in an OR connection to the values of object 6006H.

INDEX	6008
Name	Input Interrupt Mask 6 - high to low
Object Code	Array
Data Type	UNSIGNED8
Sub-Index	000
Description	Number of Elements
Access	RO
PDO Mapping	No
Default Value	0x1
Sub-Index	001
Description	Input Interrupt Mask high to low for digital Inputs 1-6
Data Type	UNSIGNED8
Access	RW
PDO Mapping	No
Default Value	0x00

7.4.7 Object 6020h: Read State 1 Input Line 1-6

Reads a single input line information.

INDEX	6020
Name	Read State 1 Input Line 1-6
Object Code	Array
Data Type	BOOLEAN
Sub-Index	000
Description	Number of Elements
Access	RO
PDO Mapping	No
Default Value	0x6
Sub-Index	001
Description	Digital Input 1
Data Type	BOOLEAN
Access	RO
PDO Mapping	No
Default Value	0x0
Sub-Index	002
Description	Digital Input 2
Data Type	BOOLEAN
Access	RO
PDO Mapping	No
Default Value	0
Sub-Index	003
Description	Digital Input 3
Data Type	BOOLEAN
Access	RO

PDO Mapping	No
Default Value	0x0
Sub-Index	004
Description	Digital Input 4
Data Type	BOOLEAN
Access	RO
PDO Mapping	No
Default Value	0x0
Sub-Index	005
Description	Digital Input 5
Data Type	BOOLEAN
Access	RO
PDO Mapping	No
Default Value	0x0
Sub-Index	006
Description	Digital Input 6
Data Type	BOOLEAN
Access	RO
PDO Mapping	No
Default Value	0x0

7.4.8 Object 6200h: Write State 6 Output Lines

Sets a group of 6 output lines as a byte of information.

INDEX	6200
Name	Write State 6 Output Lines
Object Code	Array
Data Type	UNSIGNED8

Sub-Index	000
Description	Number of Elements
Access	RO
PDO Mapping	No
Default Value	0x1
Sub-Index	001
Description	digital Outputs 1-6
Data Type	UNSIGNED8
Access	RWW
PDO Mapping	Yes
Default Value	0

7.4.9 Object 6202h: Polarity 6 Output Lines

Defines the polarity of a group of 6 output lines.

INDEX	6202
Name	Polarity 6 Output Lines
Object Code	Array
Data Type	UNSIGNED8

Sub-Index	000
Description	Number of Elements
Access	RO
PDO Mapping	No
Default Value	0x1
Sub-Index	001
Description	Polarity for digital Outputs 1-6
Data Type	UNSIGNED8
Access	RW
PDO Mapping	No
Default Value	0x00

7.4.10 Object 6206h: Error Mode 6 Output Lines

This object indicates, whether an output is set to a pre-defined error value (see 6207 h object) in case of an internal device failure or a 'Stop Remote Node' indication.

1 = output value shall take the pre-defined condition specified in 6207 h object

0 = output value shall be kept if an error occurs

INDEX	6206
Name	Error Mode 6 Output Lines
Object Code	Array
Data Type	UNSIGNED8

Sub-Index	000
Description	Number of Elements
Access	RO
PDO Mapping	No
Default Value	0x1
Sub-Index	001
Description	Fault Mode for digital Outputs 1-6
Data Type	UNSIGNED8
Access	RW
PDO Mapping	No
Default Value	0x3F

7.4.11 Object 6207h: Fault State 6 Output Lines

Output line fault state. This defines the default output state on detecting a fault condition. Defined for groups of 8 outputs. The corresponding bit must be set in the default output line mode.

INDEX	6207
Name	Fault State 6 Output Lines
Object Code	Array
Data Type	UNSIGNED8

Sub-Index	000
Description	Number of Elements
Access	RO
PDO Mapping	No
Default Value	0x1
Sub-Index	001
Description	Fault State for digital Outputs 1-6
Data Type	UNSIGNED8
Access	RW
PDO Mapping	No
Default Value	0x00

7.4.12 Object 6220h: Write State 1 Output Line 1-6

Sets a single output line information.

INDEX	6220
Name	Write State 1 Output Line 1-6
Object Code	Array
Data Type	BOOLEAN

Sub-Index	000
Description	Number of Elements
Access	RO
PDO Mapping	No
Default Value	0x6
Sub-Index	001
Description	digital Output 1
Data Type	BOOLEAN
Access	RWW
PDO Mapping	No
Default Value	0
Sub-Index	002
Description	digital Output 2
Data Type	BOOLEAN
Access	RWW
PDO Mapping	No
Default Value	0
Sub-Index	003
Description	digital Output 3

Data Type	BOOLEAN
Access	RWW
PDO Mapping	No
Default Value	0
Sub-Index	004
Description	digital Output 4
Data Type	BOOLEAN
Access	RWW
PDO Mapping	No
Default Value	0
Sub-Index	005
Description	digital Output 5
Data Type	BOOLEAN
Access	RWW
PDO Mapping	No
Default Value	0
Sub-Index	006
Description	digital Output 6
Data Type	BOOLEAN
Access	RWW
PDO Mapping	No
Default Value	0

8. SAFETY GUIDELINES

8.1 Introduction

The IO Modules have been designed developed or manufactured for conventional use in industry. They were not designed, developed and manufactured for any use involving serious risks or hazards that without the implementation of exceptionally stringent safety precautions could lead to death, injury, serious physical damage or loss of any other kind. Such risks and hazards include in particular the use of these devices to monitor nuclear reactions in nuclear power plants, as well as flight control systems, flight safety, the control of mass transportation systems, medical life support systems, and the control of weapons systems.

When using IO Modules with programmable logic controllers and when using operating and monitoring devices as control systems in conjunction with a Soft PLC, the safety precautions applying to industrial control systems (e.g. the provision of safety devices such as emergency stop circuits, etc.) in accordance with applicable national and international regulations must be observed. The same applies for all other devices connected to the system, such as drives. All tasks such as installation, commissioning and service may only be carried out by qualified personnel. Qualified personnel are persons who are familiar with the transport, mounting, installation, commissioning and operation of the product and have the appropriate qualifications. National accident prevention guidelines must be followed. The safety guidelines, connection descriptions and limit values listed in the technical data must be read carefully before installation and commissioning and must be observed.

8.2 Intended Use

Electronic devices are generally not fail-safe. In the event of a failure on the IO Modules, operating or monitoring device or uninterruptible power supply, the user is responsible for ensuring that other devices that may be connected, such as motors, are made safe.

8.3 Transport and Storage

During transport and storage, devices must be protected from excessive stress (mechanical load, temperature, humidity, aggressive atmosphere).

8.4 Installation

- The installation must take place according to the documentation.
- The IO Modules are only allowed to be installed without voltage applied and by qualified personnel.
- General safety regulations and nationally applicable accident prevention guidelines must be observed.

Electrical installation must be carried out according to the relevant guidelines (e.g. line cross section, fuse, protective ground connection).